



### **General Description**

AOZ32101MDV is a 100V half-bridge gate driver that has an integrated bootstrap diode and is designed with shoot-through protection to drive high-side and low-side N-channel MOSFETs safety. The sufficient drive capability and fast rise/fall times support system operate at high frequencies or multiple MOSFETs in parallel.

Built in under voltage lock-out protection pulls the high/low-side output low when the supply voltage is insufficient.

#### Features

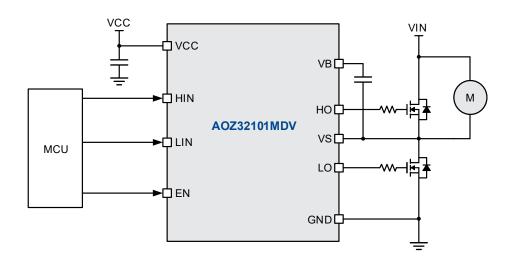
- Drives half bridge, dual N-channel MOSFET
- Integrated bootstrap diode
- 120V max. bootstrap voltage
- Input signal overlap protection
- Typical 30ns propagation delay time
- Drive 1nF load with 13ns rise/fall times with 12V VDD
- TTL compatible input
- Typical 150µA quiescent current
- Less than 5µA shutdown current
- UVLO for both high-side and low-side
- DFN 3mmx3mm 10 pin Packages

#### Applications

- Brushless DC motors
- Permanent magnet synchronous motors (PMSM)
- Power tools
- E-bike



### Typical Application





### **Ordering Information**

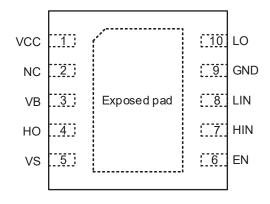
Part Number	Ambient Temperature Range	mbient Temperature Range Package	
AOZ32101MDV	-40 °C to +125 °C	10-Pin 3×3 DFN	Green

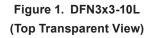


AOS products are offered in packages with Pb-free plating and compliant to RoHS standards.

Please visit https://aosmd.com/sites/default/files/media/AOSGreenPolicy.pdf for additional information.

# **Pin Configuration**





### **Pin Description**

Pin Number	Pin Name	Pin Function
1	VCC	Gate driver supply input.
2	NC	No connection.
3	VB	Bootstrap capacitor connection. An external capacitor between VB and VS for supplying high-side MOSFET is necessary.
4	НО	High-side gate driver output.
5	VS	High-side floating supply return.
6	EN	Enable/disable control.
7	HIN	Signal input for the high-side driver.
8	LIN	Signal input for the low-side driver.
9	GND	Ground.
10	LO	Low-side gate driver output.



# Absolute Maximum Ratings

Exceeding the Absolute Maximum ratings may damage the device.

Parameter	Rating
Supply Voltage (VCC)	-0.3 V to 20 V
SW Voltage (VS)	-5V to 105V
Bootstrap Voltage (VB)	-0.3 V to 120 V
VB to VS	-0.3V to 18V
НО	-0.3 V to (VB-VS) +0.3 V
LO to GND	-0.3V to (VCC+0.3V)
All Other Pins	-0.3 V to 20 V
Junction Temperature (T <sub>J</sub> )	+150 °C
Storage Temperature (T <sub>S</sub> )	-65 °C to +150 °C
ESD Rating	1kV

## **Maximum Operating Conditions**

The device is not guaranteed to operate beyond the Maximum Recommended Operating Conditions.

Parameter	Rating
Supply Voltage (VCC)	+5.5V to 18V
SW Voltage (VS)	-1.0 V to 100 V
Voltage Slew Rate (VS)	5 V/ns
Ambient Temperature (T <sub>A</sub> )	-40 °C to +125 °C
Package Thermal Resistance $(\Theta_{JA})$ $(\Theta_{JC})$	46 °C/W 8.6 °C/W

# **Electrical Characteristics**

 $T_A = 25 \degree$ C, VCC = VB-VS=12V,  $V_{GND}$ =VS = 0V,  $V_{EN}$ =3.3V, No load at HO and LO, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Мах	Units				
Supply Current										
I <sub>SHDN</sub>	VCC shutdown current	VEN=0			1	μA				
I <sub>VCC_Q</sub>	VCC quiescent current	LIN=HIN=0		150	180	μA				
I <sub>VCC_0</sub>	VCC operating current	fsw=50kHz		320	400	μΑ				
I <sub>VB_Q</sub>	Floating driver quiescent current	LIN=0, HIN=0 or 1		50	70	μA				
I <sub>VB_O</sub>	Floating driver operating current	fsw=50kHz		100	150	μΑ				
I <sub>LK</sub>	Leakage current	VB=VS=100V		0.1	1	μA				
Inputs				1						
V <sub>IN_H</sub>	LIN/HIN high logic input voltage		2.4			V				
V <sub>IN_L</sub>	LIN/HIN low logic input voltage				1	V				
V <sub>IN_HYS</sub>	LIN/HIN hysteresis			0.6		V				
R <sub>IN</sub>	LIN/HIN internal pull-down resistance			200		kΩ				



# **Electrical Characteristics** (Continued)

 $T_A = 25 \degree$ C, VCC = VB-VS=12V,  $V_{GND}$ =VS = 0V,  $V_{EN}$ =3.3V, No load at HO and LO, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
Under Voltag	e Protection			1	1	1
VCC <sub>R</sub>	VCC rising threshold		4.6	5	5.4	V
VCC <sub>F</sub>	VCC falling threshold		4.1	4.5	4.9	V
VB <sub>R</sub>	(VB-VS) rising threshold		4.6	5	5.4	V
VB <sub>F</sub>	(VB-VS) falling threshold		4.1	4.5	4.9	V
V <sub>EN_L</sub>	EN Input Logic Low				0.6	V
V <sub>EN_H</sub>	EN Input Logic High		1.5			V
V <sub>EN_HYS</sub>	EN Hysteresis			100		mV
	EN Input Ourrent	V <sub>EN</sub> =2V, T <sub>A</sub> =+25°C		10		μA
I <sub>EN</sub>	EN Input Current	V <sub>EN</sub> =5V			35	μA
R <sub>EN</sub>	EN internal pull-down resistance			450		kΩ
Bootstrap Die	ode			1	1	1
V <sub>F1</sub>	Bootstrap diode VF @ 100µA			0.5		V
V <sub>F2</sub>	Bootstrap diode VF @ 80mA			2.7		V
R <sub>D</sub>	Bootstrap diode dynamic R	V <sub>F</sub> =1V and 2V		28		Ω
Low-side Gat	te Driver		I	1		1
V <sub>LO_L</sub>	Low level output voltage	I <sub>O</sub> =100mA		0.15	0.22	V
V <sub>LO_H</sub>	High level output voltage to rail	I <sub>O</sub> =100mA		0.45	0.6	V
		V <sub>LO</sub> =0V, VCC=4.5V		0.8		А
ILO_SOURCE	Peak pull-up current	V <sub>LO</sub> =0V, VCC=12V		2		Α
		V <sub>LO</sub> =0V, VCC=16V		2.5		A
		V <sub>LO</sub> =VCC=4.5V		1.2		A
I <sub>LO_SINK</sub>	Peak pull-down current	V <sub>LO</sub> =VCC=12V		3		A
		V <sub>LO</sub> =VCC=16V		3.2		A
Floating Gate	e Driver			1	1	1
V <sub>HO_L</sub>	Low level output voltage	I <sub>O</sub> =100mA		0.15	0.22	V
V <sub>HO_H</sub>	High level output voltage to rail	I <sub>O</sub> =100mA		0.45	0.6	V
		V <sub>HO</sub> =0V, VB-VS=5V		0.8		Α
I <sub>HO_SOURCE</sub>	Peak pull-up current	V <sub>HO</sub> =0V, VCC=12V		2		A
		V <sub>HO</sub> =0V, VCC=16V		2.5		A
		V <sub>HO</sub> =VB-VS=5V		1.2		A
I <sub>HO_SINK</sub>	Peak pull-down current	V <sub>HO</sub> =VCC=12V		3.1		A
		V <sub>HO</sub> =VCC=16V		3.5		A

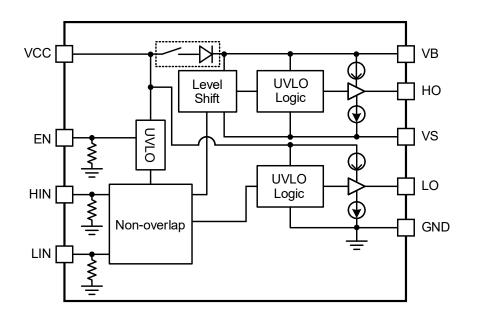


## **Electrical Characteristics** (Continued)

 $T_{A} = 25 \text{ °C}, \text{ VCC} = \text{VB-VS} = 12 \text{V}, \text{ } \text{V}_{\text{GND}} = \text{VS} = 0 \text{V}, \text{ } \text{V}_{\text{EN}} = 3.3 \text{V}, \text{ No load at HO and LO, unless otherwise specified.}$ 

Symbol	Parameter	Min	Тур	Мах	Units					
Switching Characteristics										
Low-side Gat	e Driver									
t <sub>PDF_L</sub>	Turn-off propagation delay LIN falling to LO falling			20		ns				
t <sub>PDR_L</sub>	Turn-on propagation delay LIN rising to LO rising			20		ns				
t <sub>R_L</sub>	LO rise time	C <sub>L</sub> =1nF		12		ns				
t <sub>F_L</sub>	LO fall time	C <sub>L</sub> =1nF		9		ns				
Floating Gate	Driver									
t <sub>PDF_H</sub>	Turn-off propagation delay HIN falling to HO falling			20		ns				
t <sub>PDR_H</sub>	Turn-on propagation delay HIN rising to HO rising			18		ns				
t <sub>R_H</sub>	HO rise time	C <sub>L</sub> =1nF		12		ns				
t <sub>F_H</sub>	HO fall time	C <sub>L</sub> =1nF		9		ns				
T <sub>off_H</sub>	HO minimun off time			550	650	ns				

# **Functional Block Diagram**







# **Timing Diagram**

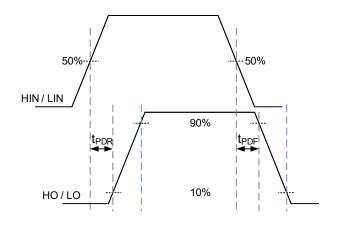


Figure 2. Timing Diagram for AOZ32101MDV



### **Detailed Description**

#### VCC Power Up and UVLO

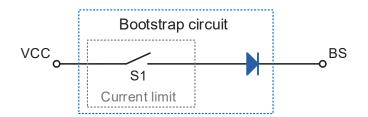
In order to ensure the normal operation of the gate driver, if the EN pin is pulled high (normal working state), the gate driver will not work before VCC is higher than the UVLO rising threshold (about 5V), until VCC>5V, the gate driver can work normally. When VCC drops to the UVLO falling threshold (about 4.5V), gate driver shuts down.

#### **VB UVLO**

The voltage of the Bootstrap capacitor(VB-VS) is supplied to the high-side gate driver. VB-VS must be greater than (VB-VS) rising threshold to make the high-side gate driver start working. If it is less than (VB-VS) falling threshold, there will be no output.

#### **Bootstrap Circuit**

Different from the traditional bootstrap architecture, in addition to the diode on the bootstrap path, AOZ32101MDV also adds a switch (S1) to limit the current. When the charging current exceeds 100mA, it is limited to 100mA. The purpose is to limit the large current of the bootstrap charging moment. In addition, if the charging current is too large, the reverse recover current of the diode will also be too large. The above two reasons may cause damage to the circuit, so the current limiting function can effectively protect the bootstrap diode.





#### **EN Pin**

The EN pin is used to enable the gate driver. When the voltage of the EN pin is greater than the EN Logic High voltage, the gate driver works normally. When the EN pin is floating or connected to GND, the gate driver does not work.

The EN pin is internally connected to GND through a 450 K $\Omega$  pull-down resistor. When the EN pin is not used, the EN pin can be connected to VCC through an external pull-up resistor. The recommended resistor value is 10 K $\Omega$ .

In addition, it is recommended to input the HIN/LIN signal after the EN pin voltage is higher than VEN\_H, and to turn off the HIN/LIN signal before the EN pin voltage is lower than VEN\_L.

It is recommended that the EN signal transitions from 2V to 0V in a time not exceeding 1ms.

#### **Control Logic**

When EN is pulled high, HO and LO follow their respective HIN and LIN signals through the gate driver to drive MOSFETs, and the internal circuit will also judge whether the HIN/LIN signals are high at the same time to avoid shoot-through of High/Low-side MOSFETs. The truth table of the control logic is as follows.

#### Table 1. Truth Table of the Control Logic

EN	HIN	LIN	НО	LO
	L	L	L	L
1	Н	L	L	L
	L	Н	L	L
	Н	Н	L	L
	L	L	L	L
	Н	L	Н	L
Н	L	Н	L	Н
	Н	Н	L	L

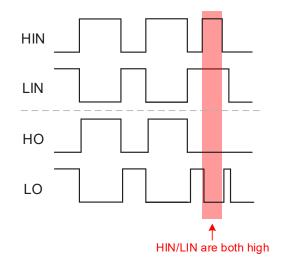


Figure 4. Overlap Prevention



### **Application Circuit and Layout Guidelines**

The AOZ32101MDV has a driving capability of over 2A. A larger driving capability implies that there will be greater noise generated in the circuit when the MOSFET switches on and off moments. If the input voltage increases or the load becomes heavier, the noise will also increase.

GND is the reference potential for the entire system, while VS is the reference potential for the high side driver. If the spikes generated by the switch are too large, it may potentially affect the system.

In order to improve the stability of the system, you can refer to the following circuits and layout when designing the circuit.

- Connecting a low ESR bypass capacitor in parallel between (VCC to GND)(C1) and (VB to VS)(C2) can effectively reduce the noise in the driver's power supply. The recommended value is 10nF. This bypass capacitor must be placed close to the device leads.
- 2. EN, HIN, LIN are signal pins. It is recommended to add an RC filter circuit to minimize the impact of noise on the signals received by the driver. The suggested values for R and C are R=10 $\Omega$  and C=33pF. If the application has a very small duty cycle and there is signal distortion, the values of R and C can be reduced.
- If the application has a high input voltage or a relatively heavy load, it is recommended to add diodes between (HO to VS)(D1) and (LO to GND)(D2). When GND and VS have large negative voltages, the voltage can be clamped must be located close to the device pins.

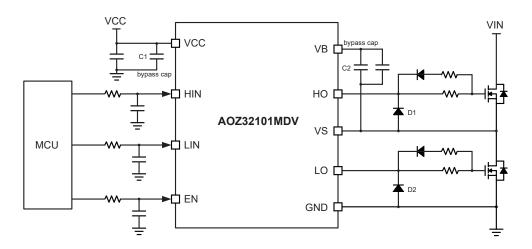


Figure 5. Recommended Application Circuit

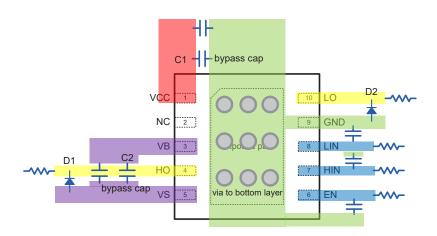
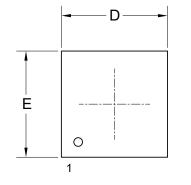
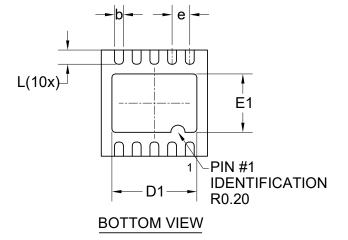


Figure 6. Recommended PCB Layout

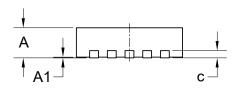


# Package Dimensions, DFN3x3-10L



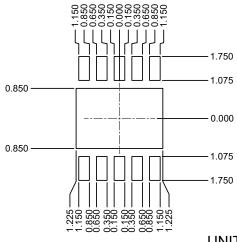






SIDE VIEW

# RECOMMENDED LAND PATTERN



	DIMENSI	ONS IN MIL	LIMETERS	DIME	NSIONS IN	INCHS
SYMBOL	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
А	0.80	0.85	0.90	0.031	0.033	0.035
A1	0.00		0.05	0.000		0.002
b	0.20	0.25	0.30	0.008	0.010	0.012
с		0.203 REF			0.008 RE	EF.
D	2.90	3.00	3.10	0.114	0.118	0.122
D1	2.30	2.40	2.50	0.091	0.094	0.098
E	2.90	3.00	3.10	0.114	0.118	0.122
E1	1.55	1.65	1.75	0.061	0.065	0.069
е		0.50 BSC			0.002 BSC	
L	0.30	0.40	0.50	0.012	0.016	0.020

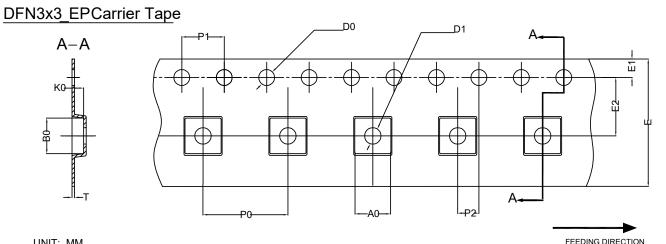
UNIT: mm

### NOTE

1. CONTROLLING DIMENSION IS MILLIMETER. CONVERTED INCH DIMENSIONS ARE NOT NECESSARILY EXACT.

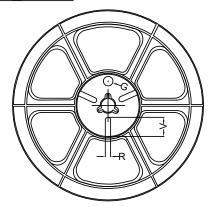


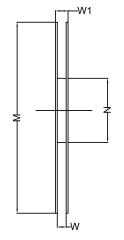
# Tape and Reel Dimensions, DFN3x3-10L

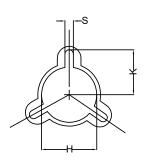


UNIT: MM											FEEDING	DIRECTION
PACKAGE	A0	BO	KO	D0	D1	Ш	E1	Ð	P0	P1	P2	Т
DFN3x3_EP	3.40 ±0.10	3.35 ±0.10	1.10 ±0.10	1.50 +0.10 -0	1.50 +0.10 -0	12.00 ±0.30	1.75 ±0.10	5.50 ±0.05	8.00 ±0.10	4.00 ±0.10	2.00 ±0.05	0.30 ±0.05

### DFN3x3\_EP Reel





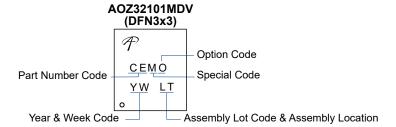


UNIT: MM

TAPE SIZE	REEL SIZE	М	Ν	W	W1	Н	К	S	G	R	V
12 mm	Ø330	Ø330.00 ±0.50	Ø97.00 ±0.10	13.00 ±0.30	17.40 ±1.00	Ø13.00 +0.50 -0.20	10.60	2.00 ±0.50			



# **Part Marking**



Part Number	Description	Code
AOZ32101MDV	Green Product	CEM0

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2. A critical component in any component of a life support, device, or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.